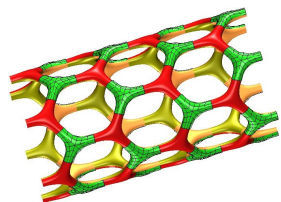
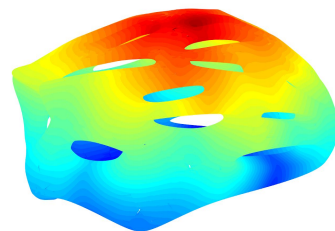
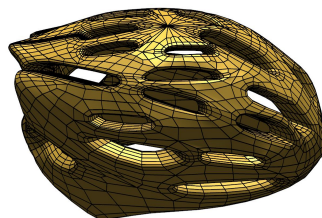
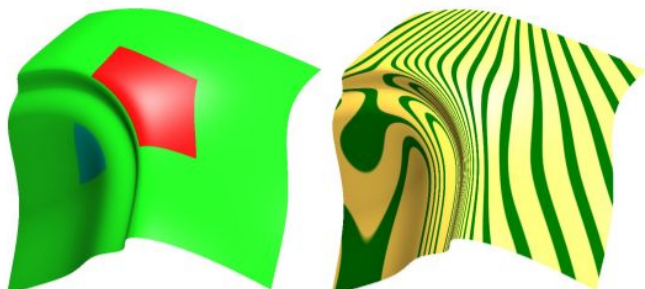


Polyhedral-net Splines for Geometry and Analysis

Jorg Peters



Jorg Peters U of Florida

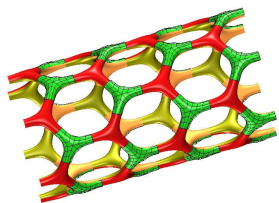
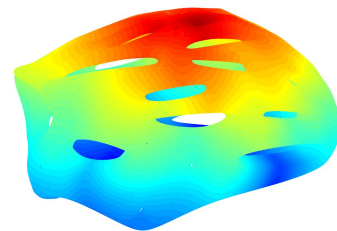
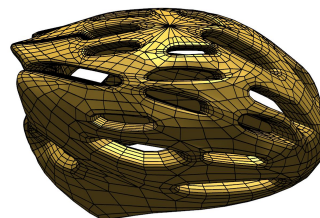
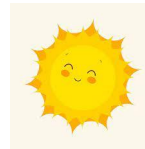
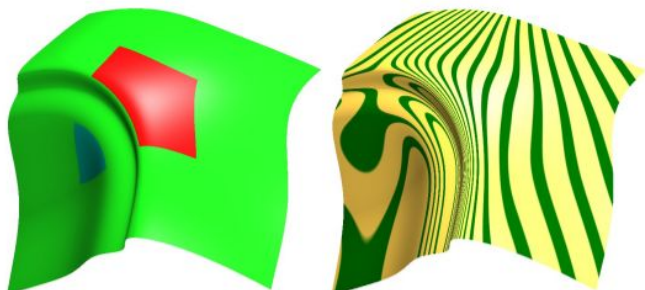
CIRM 2024

Joint work with
K Karciauskas,
Bhaskar Mishra
Seth Barber

<https://www.cise.ufl.edu/~jorg/>

Polyhedral-net Splines for **Geometry** and Analysis

Jorg Peters



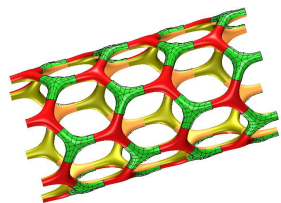
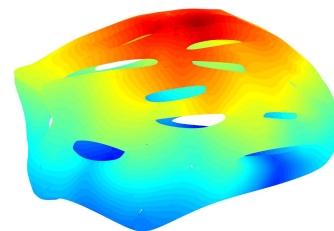
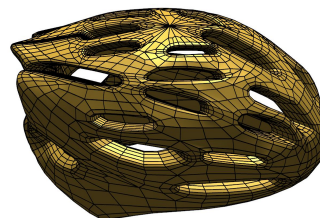
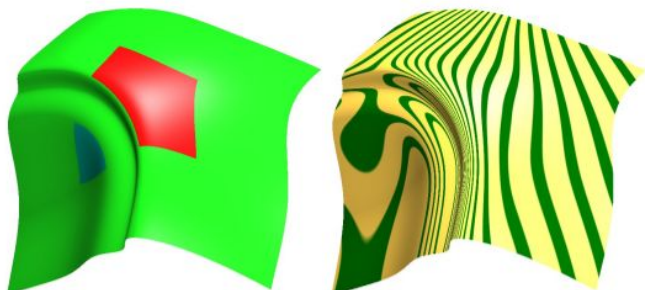
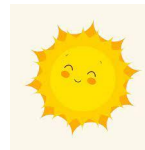
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Polyhedral-net Splines for Geometry and **Analysis**

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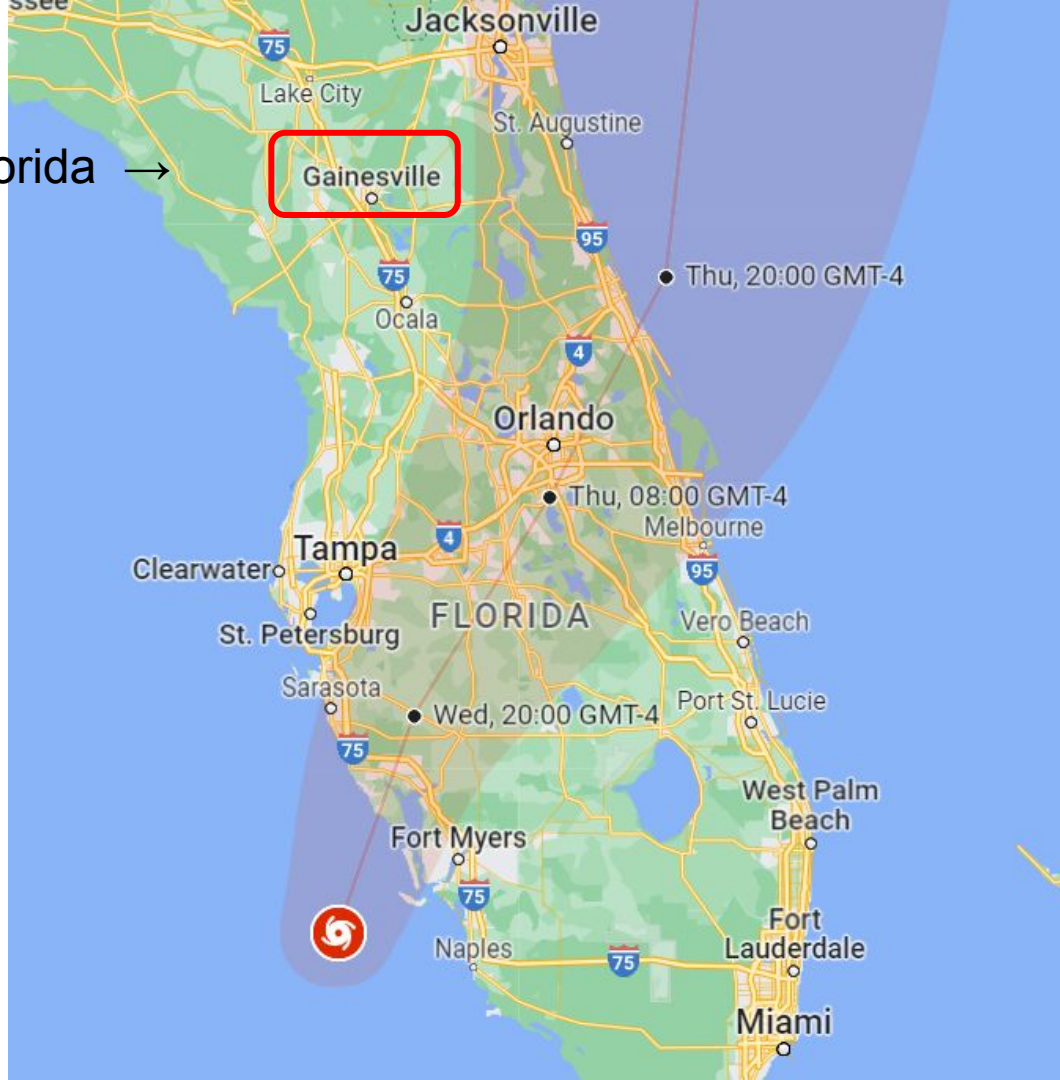


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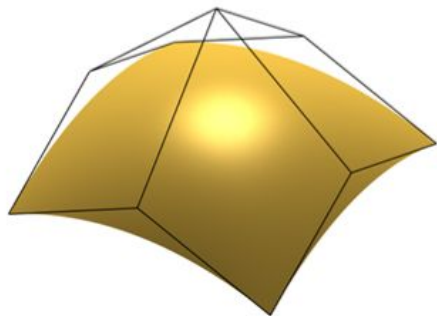
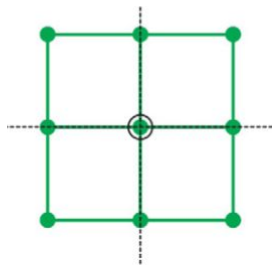
<https://www.cise.ufl.edu/~jorg/>

U of Florida →



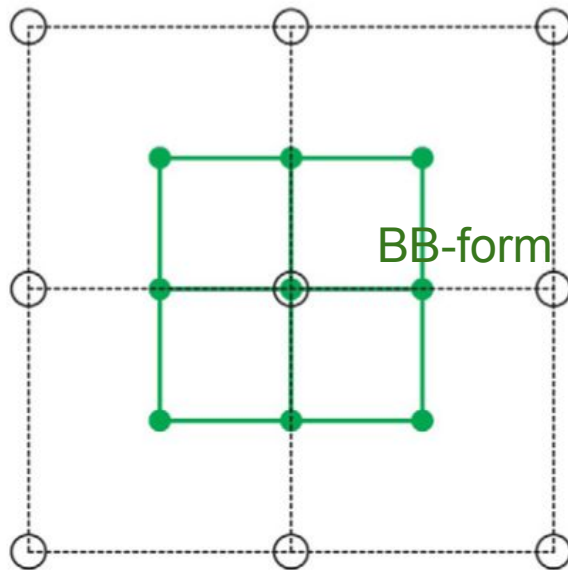
Recall: B-spline & BB-form

Interpolate
corners



(a) BB-net and bi-2 patch

BB=Bernstein-Bezier

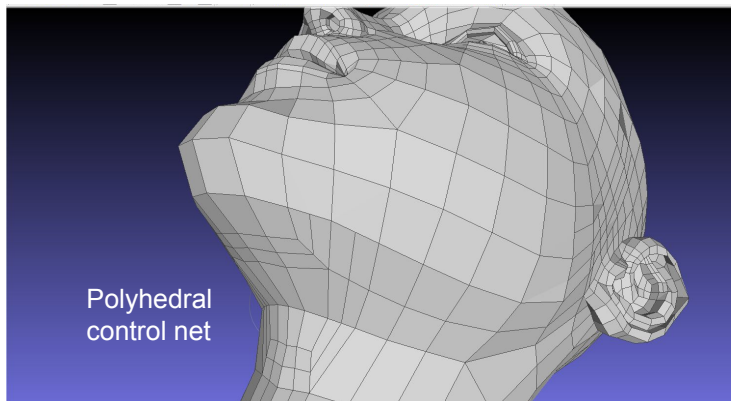


(uniform)
B-spline

$$\sum_i^n c_i b_i(t)$$
$$\sum_i^n c_i b_i(t)$$

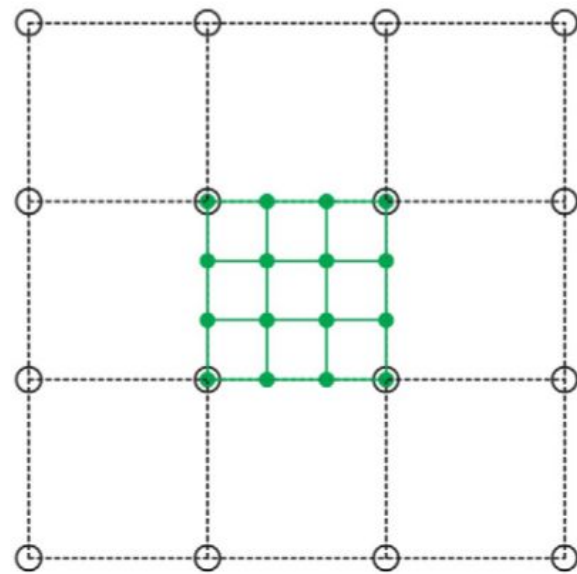
(b) bi-2 spline nets

Polyhedral-net Splines (Geometry)



B-spline: built-in smoothness

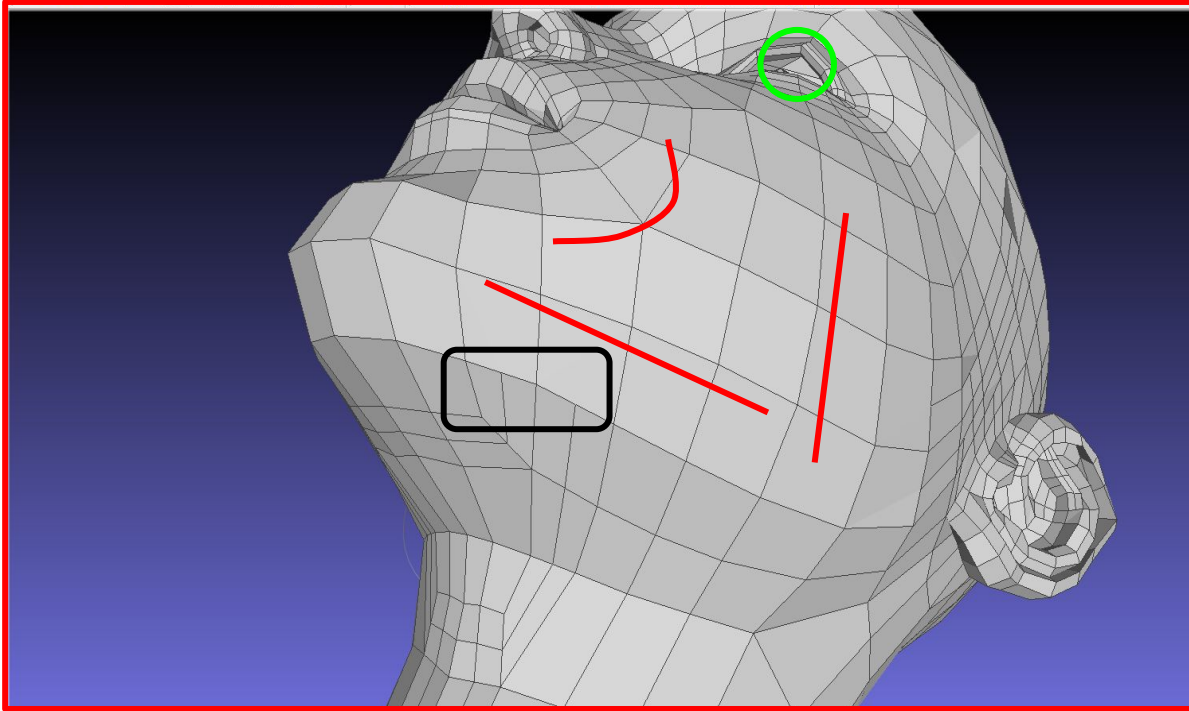
$$\sum_i^n a_i b_i(t)$$
$$\sum_i^n c_i b_i(t)$$



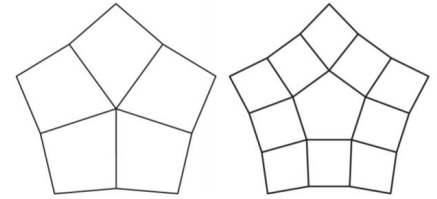
(c) bi-3 spline nets

Polyhedral net patterns

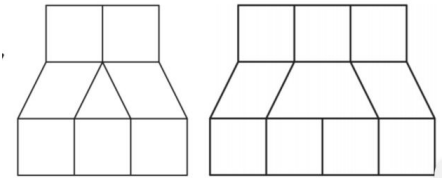
PnS Jorg Peters



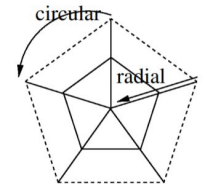
merge parameter directions



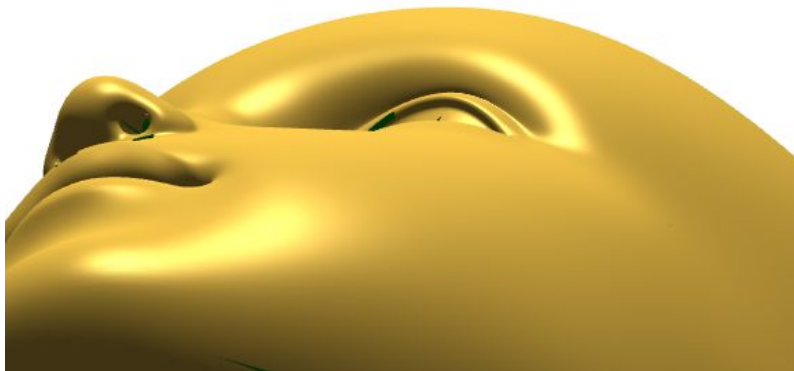
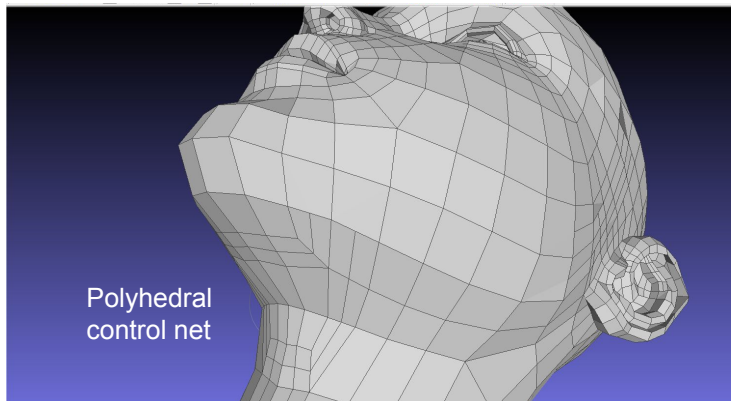
transition between coarse and fine meshes



polar



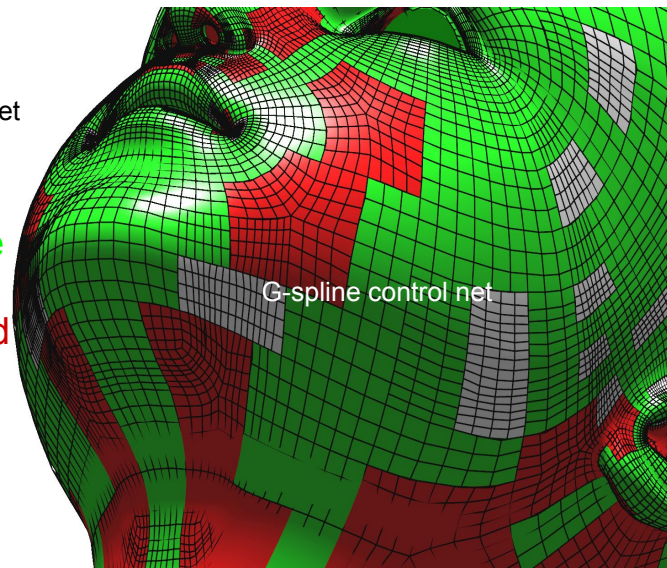
Polyhedral-net Splines



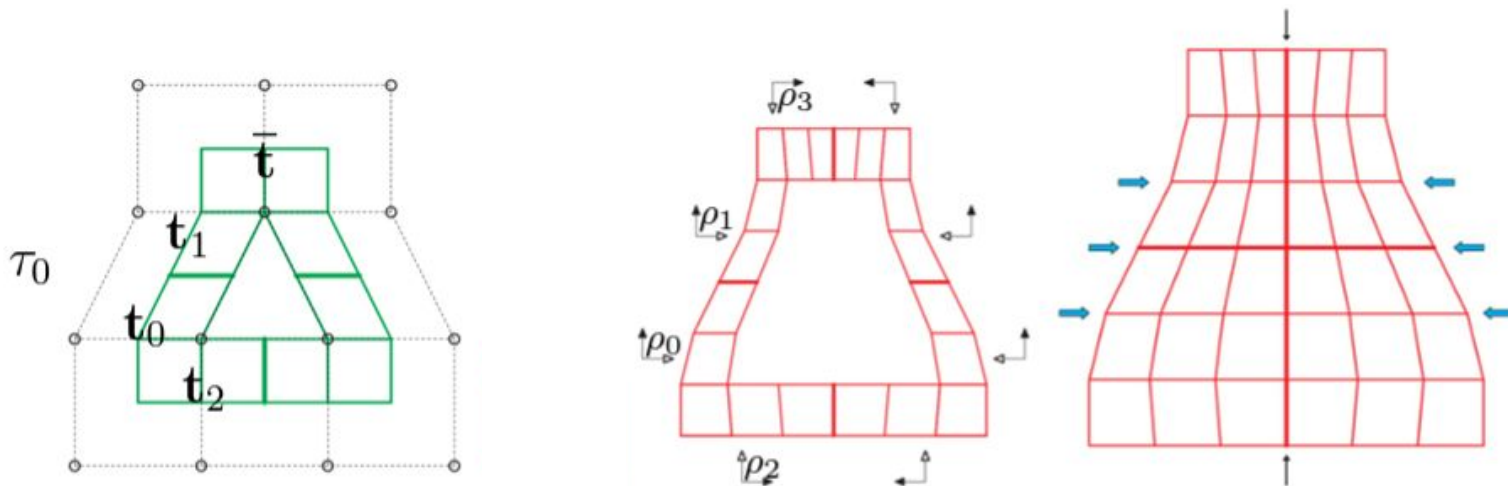
PnS3

Bezier control net

Bi-3 spline
T-junction
multi-sided



Tensor borders (Hermite data, ribbons,...)



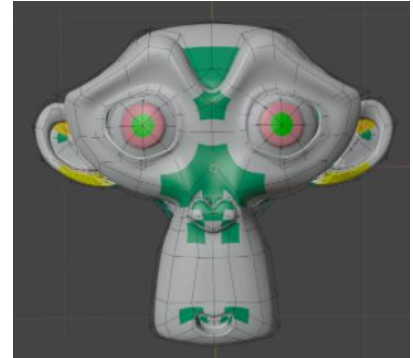
config	$\alpha(u)$	$[\dots, a_j(u), \dots]$	$[\dots, \beta_j, \dots]$	BB-coefficients of reparameterization
τ_0	$1 - \frac{u}{2}$	$[\alpha(\frac{u}{2}), \alpha(\frac{1}{2} + \frac{u}{2}), 1, 1]$	$[0, 0, -1, 2]/4$	
τ_1	$1 - \frac{u}{3}$	$[\alpha(\frac{u}{2}), \alpha(\frac{1}{2} + \frac{u}{2}), 1, 1, 1, 1]$	$[0, 0, -2, 2, 3, -3]/12$	
τ_2	$1 - \frac{u}{3}$	see text above Table 1	$[-2, 2, -2, 2, 3, -3, 3, -3]/18$	

Table 1: Reparameterizations (change of variables) $\rho_j(u, v) := (u + b_j(u)v, a_j(u)v)$ as indexed in Fig. 4c.

➤ Blender Add-on

Disclaimer:

- Blender offers only uniform bi-3 splines!
- Blender splines: Slow initialization!
- Blender renders incorrectly: evaluates lines, forms quads, uses approximate normals of quads → export as iges and use FreeCAD



Polyhedral-net Splines (PnS2)

- Blender Add-on
 - Blender offers only uniform bi-3 splines!
 - Blender splines: Slow initialization!
 - Blender renders incorrectly: evaluates lines, forms quads, uses approximate normals of quads

- **AMC ToMS: C++ Library,**
 - Export to: IGES ([freeCAD](#)), bv ([Bezierview](#))
 - **Analysis add-on**



Polyhedral-net Splines

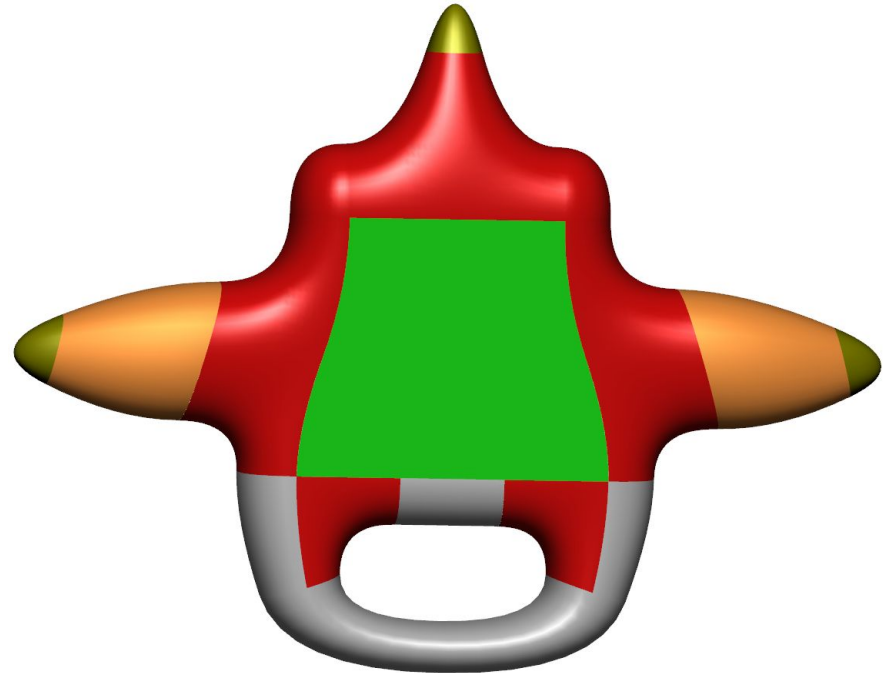
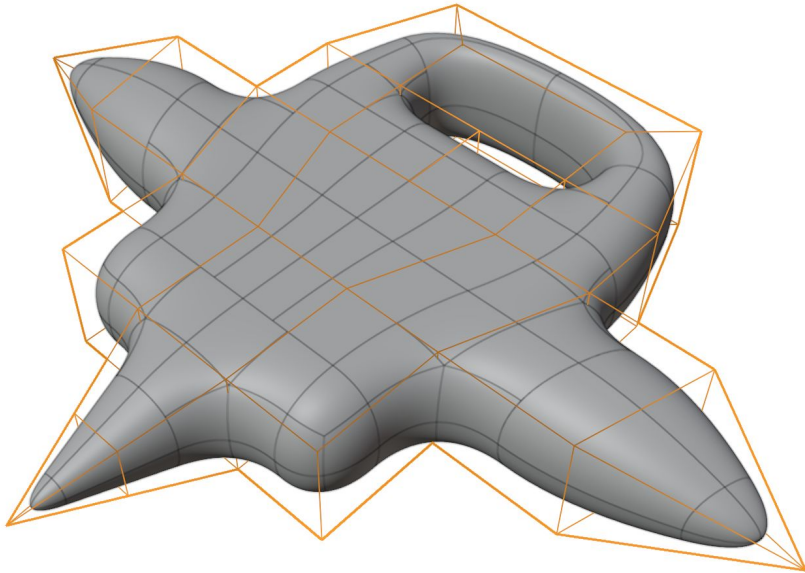


(a) Input: cube.obj

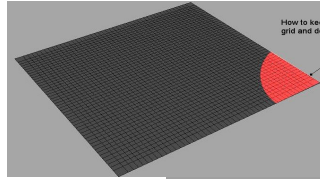
(b) surface

PnS shapes

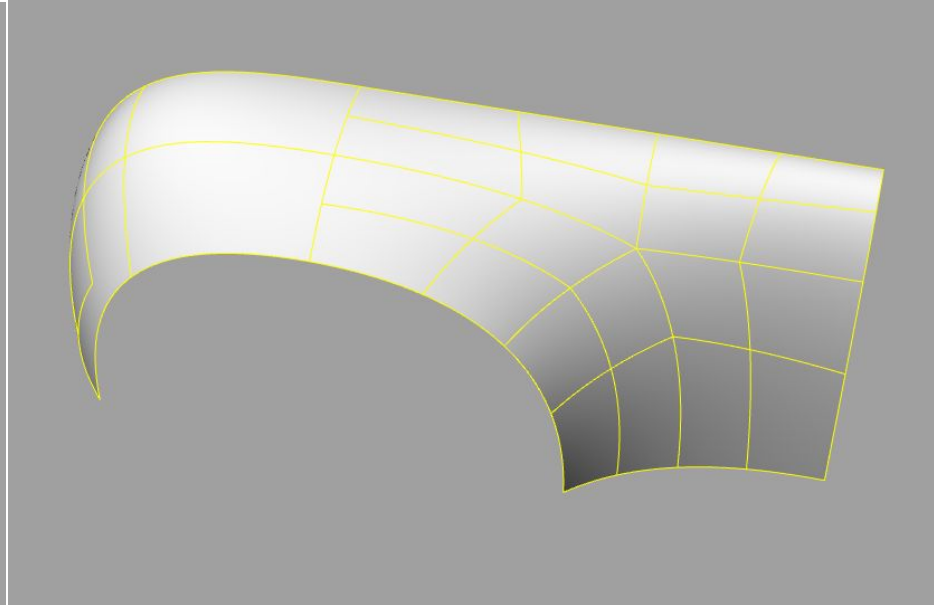
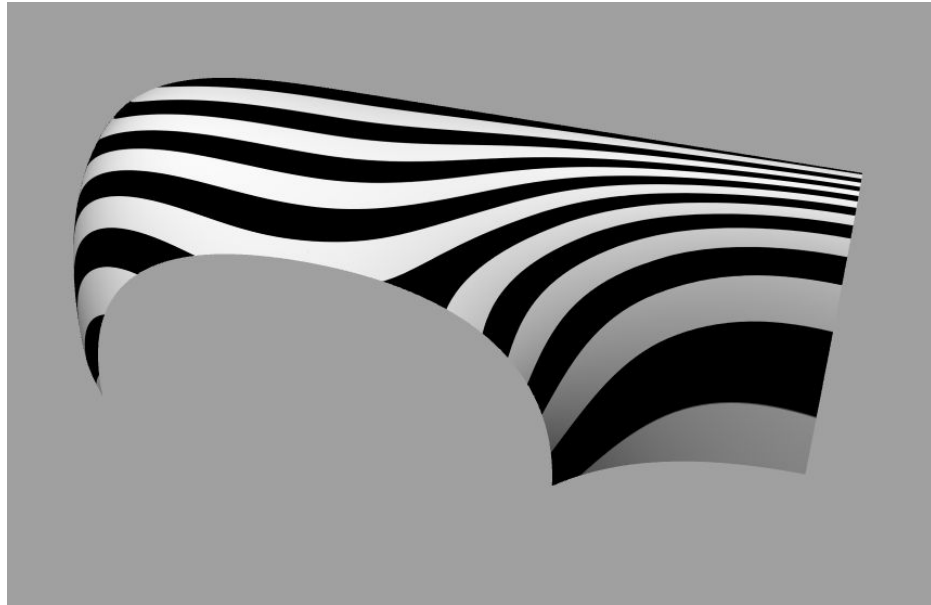
Polyhedral-net Splines Jorg Peters



PnS avoids (one type of) trimming



Trim → not exact (pixel dropout under zoom)

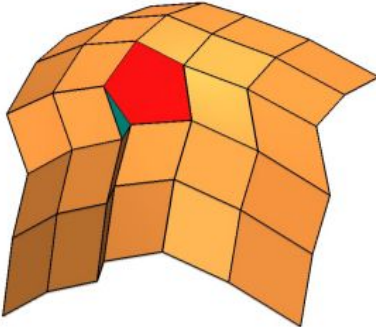


Polyhedral-net Splines: Alternative to (some types of) trimming

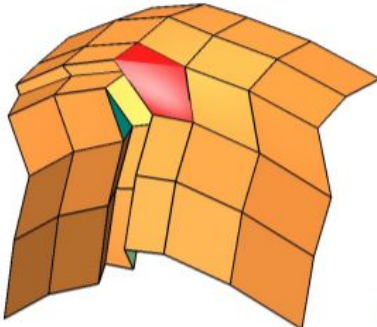
Spline Polyhedral Mesh Jorg Peters



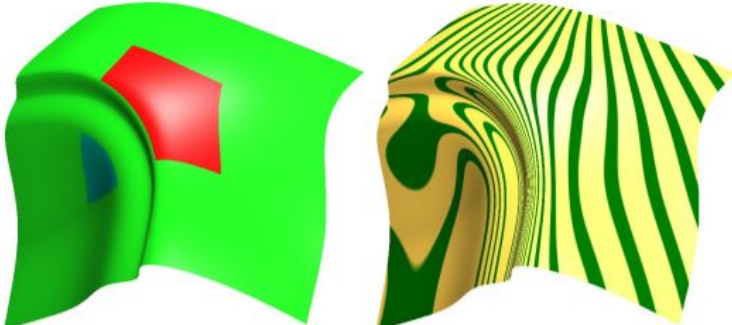
(a) sketch



(b) input with feature



(c) groove inserted



Designer: "Polyhedral Splines are better than Subdivision Surfaces"

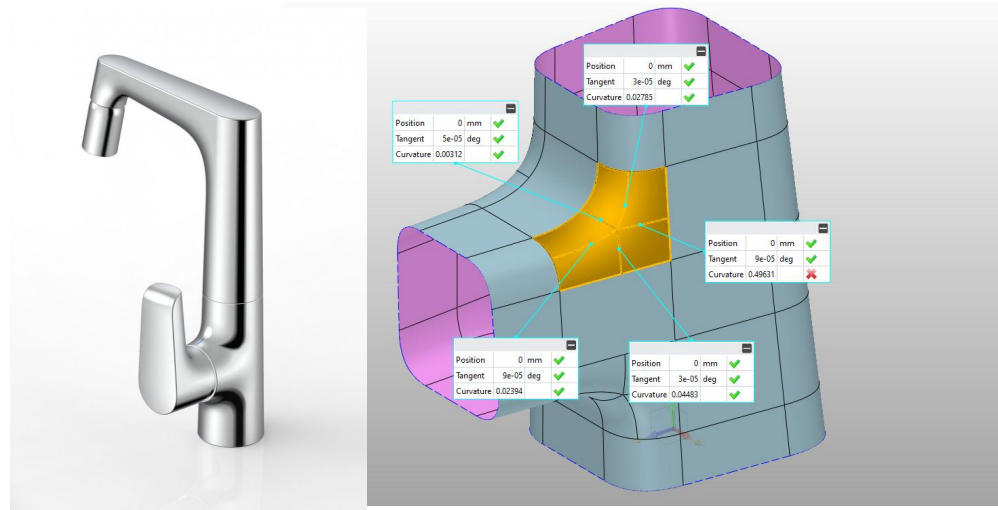
PnS3



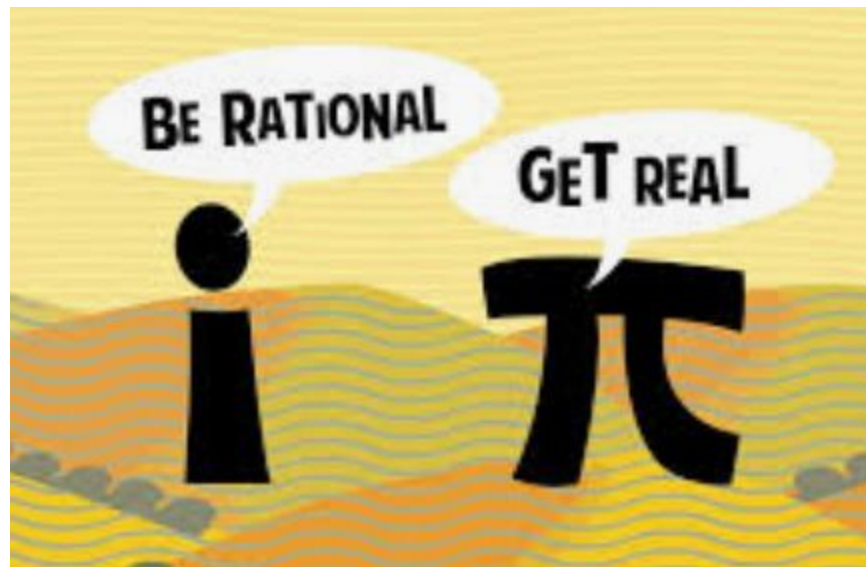
Tony Black



PnS2



Geometry



Analysis

A good idea: use splines for geometry and analysis

Splines on Meshes with Irregularities Jorg Peters

COMPUTER METHODS IN APPLIED MECHANICS AND ENGINEERING 44 (1984) 247-267
NORTH-HOLLAND

1983

SHAPE OPTIMAL DESIGN USING B-SPLINES

V. BRAIBANT and C. FLEURY

Aerospace Laboratory of the University of Liège, B-4000 Liège, Belgium

Received 28 January 1983

Revised manuscript received 21 December 1983

Shape optimal design of an elastic structure is formulated using a design element technique. It is shown that Bezier and B-spline curves, typical of the CAD philosophy, are well suited to the definition of design elements. Complex geometries can be described in a very compact way by a small

the Bezier or the B-spline techniques. Therefore the shape variables are no longer the positions of the 4, 8 or 12 nodes of an isoparametric two-dimensional element, but the points which control two families of curves whose Cartesian product defines the design element.

A good idea: use splines for geometry and analysis

SHAPE OPTIMAL DESIGN USING B-SPLINES

V. BRAIBANT and C. FLEURY

Aerospace Laboratory of the University of Liège, B-4000 Liège, Belgium

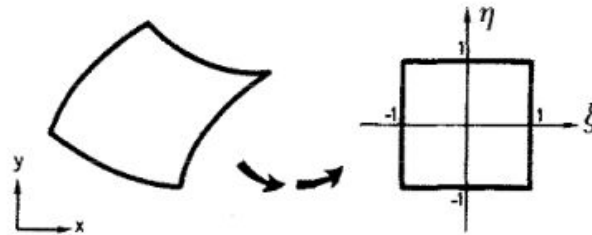
Received 28 January 1983

Revised manuscript received 21 December 1983

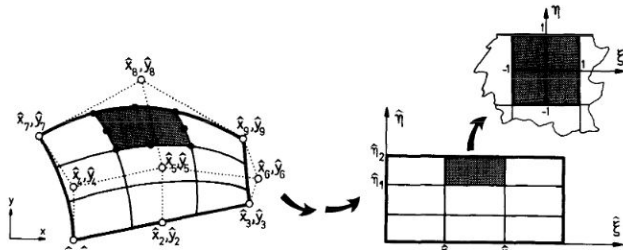
Shape optimal design of an elastic structure is formulated using a design element technique. It is shown that Bezier and B-spline curves, typical of the CAD philosophy, are well suited to the definition of design elements. Complex geometries can be described in a very compact way by a small

in which u_i and v_i are the nodal displacements. The formulation is isoparametric. In the subsequent calculus, the derivatives of the shape functions N_i with respect to the structural coordinates x, y will be needed:

$$\begin{bmatrix} N_{i,x} \\ N_{i,y} \end{bmatrix} = [J_0^{-1}] \begin{bmatrix} N_{i,\xi} \\ N_{i,\eta} \end{bmatrix} \quad (3.14)$$



Physical Domain Parametric Domain



Physical Domain Parametric Domain

A good idea: use splines for geometry and analysis

Splines on Meshes with Irregularities Jorg Peters

Computers & Structures Vol. 48, No. 1, pp. 23–32, 1993
Printed in Great Britain.

0045-7949/93 \$6.00 + 0.00
© 1993 Pergamon Press Ltd

1992

ISOPARAMETRIC SPLINE FINITE STRIP FOR PLANE STRUCTURES

F. T. K. AU and Y. K. CHEUNG

Department of Civil and Structural Engineering, University of Hong Kong, Hong Kong

(Received 4 May 1992)

Abstract—The isoparametric spline finite strip methods for Mindlin plate bending, plane stress and plane strain problems are presented. The essence of the method lies in the use of uniform cubic B-spline curves in the modelling of the geometry and representation of the displacement field. In this paper, the general

A. Y. T. Leung and F. T. K. Au, Spline finite elements for beam and plate. *Comput. Struct.* **37**, 717–729 (1990).

A good idea: use splines for geometry and analysis

PnS Jorg Peters

Finite Elements in Analysis and Design 15 (1993) 11–34
Elsevier

11

FINEL 340

1993

COMPUTER METHODS IN APPLIED MECHANICS AND ENGINEERING 71 (1988) 99–116
NORTH-HOLLAND

SHAPE OPTIMAL DESIGN USING HIGH-ORDER ELEMENTS

Y.K. SHYY and C. FLEURY

*Mechanical, Aerospace and Nuclear Engineering Department, University of California at Los Angeles,
Los Angeles, CA 90024, U.S.A.*

and

K. IZADPANAH

The MacNeal-Schwendler Corporation, Los Angeles, CA 90041, U.S.A.

Received 17 December 1987

The coupling of geometric descriptions and finite elements using NURBs – A study in shape optimiz

Uwe Schramm and Walter D. Pilkey

*Department of Mechanical, Aerospace and Nuclear Engineering, University of Virginia,
Charlottesville, VA 22903, USA*

Abstract. This paper presents a geometry based approach for coupling CAD with finite element methods. Non uniform rational B-splines (NURBs), known from computer aided geometric design, are used to describe the shape of a structure. NURB curves and surfaces and Gordon surfaces defined by NURB curves are introduced for design description. These geometries are used directly for the mapping of finite elements and for parameterization for the optimization of the structural shape. The cross-sectional torsion problem is employed

A good idea: use splines for geometry and analysis

PnS Jorg Peters



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Comput. Methods Appl. Mech. Engrg. 194 (2005) 4135–4195

**Computer methods
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engineering**

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2004

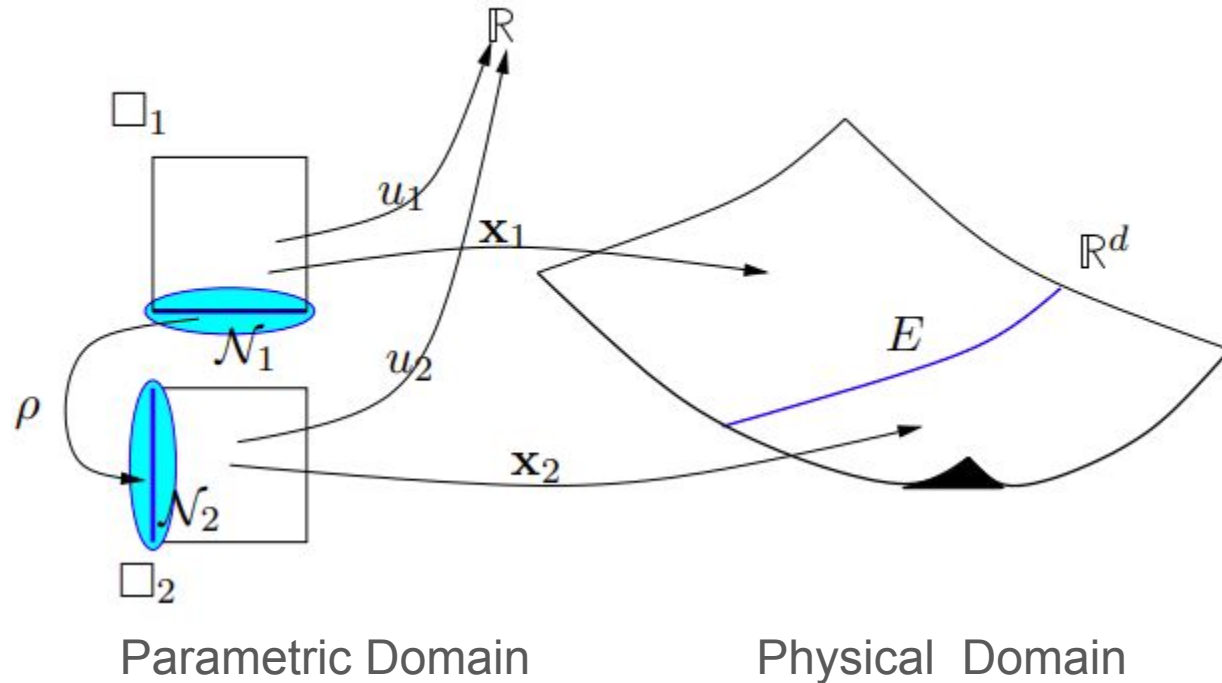
Isogeometric analysis: CAD, finite elements, NURBS,
exact geometry and mesh refinement

T.J.R. Hughes *, J.A. Cottrell, Y. Bazilevs

*Institute for Computational Engineering and Sciences, The University of Texas at Austin, 201 East 24th Street,
1 University Station C0200, Austin, TX 78712-0027, United States*

Received 28 September 2004; accepted 20 October 2004

Higher order isoparametric analysis (IGA)



Standard Galerkin weighted by first fundamental form

$$K_{ij} := \sum_{\alpha} \int_{\square} (\nabla \phi_i)^{\mathfrak{t}} (J_{\alpha}^{\mathfrak{t}} J_{\alpha})^{-1} (\nabla \phi_j) J d\square, \quad \mathbf{f}_i := \sum_{\alpha} \int_{\square} f \phi^i J d\square.$$

1st fundamental form

$$J_{\alpha} := \nabla_{\mathbf{s}} \mathbf{X}_{\alpha} = \begin{bmatrix} \partial_s x & \partial_t x \\ \partial_s y & \partial_t y \end{bmatrix} \in \mathbb{R}^{2 \times 2} \text{ and } J := \sqrt{\det(J_{\alpha}^{\mathfrak{t}} J_{\alpha})} \in \mathbb{R},$$

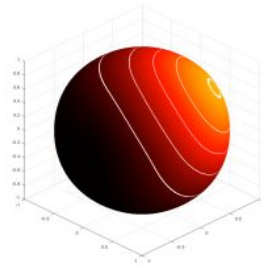
Polyhedral-net Splines & Eng Analysis



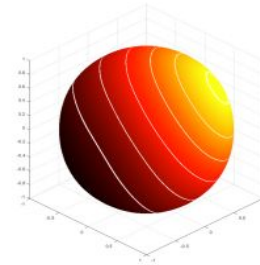
(a) Input: cube.obj

(b) surface

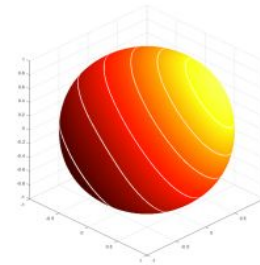
8 dof



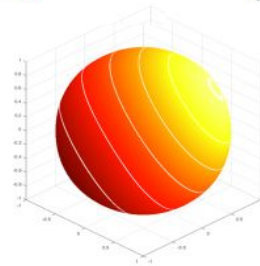
(a) $t = 0$



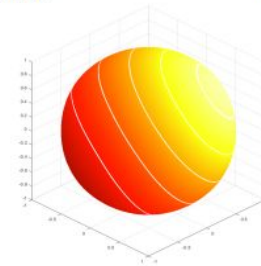
(b) $t = 0.25$



(c) $t = 0.5$



(d) $t = 0.75$

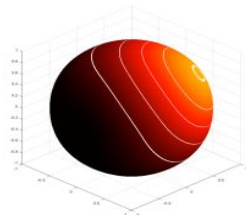


(e) $t = 1$

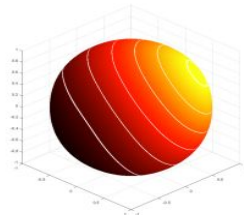
Geometry and Computing using Polyhedral-net Splines

Jorg Peters

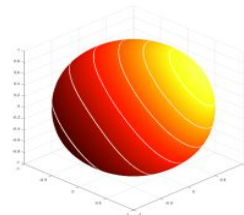
8 dof vs



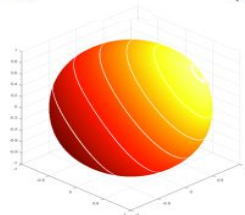
(a) $t = 0$



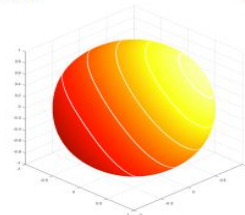
(b) $t = 0.25$



(c) $t = 0.5$



(d) $t = 0.75$



(e) $t = 1$

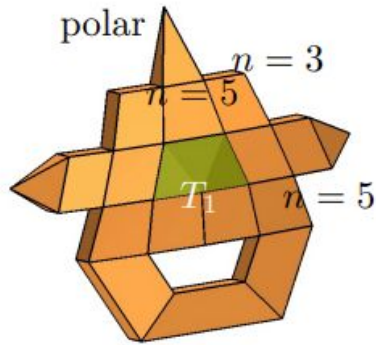
8x3 pieces
8x8 triangulation
degree 2 C0
volumetric

...

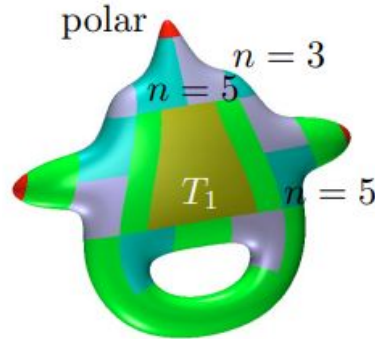
43008 dof

Geometry and Computing using Polyhedral-net Splines

Jorg Peters



(a) polyhedral control net



(b) spline patch layout



(a) $t = 0.5$



(b) $t = 0.75$



(c) $t = 1$

Geometry and Computing using Polyhedral-net Splines

Jorg Peters



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<https://www.pnspline>

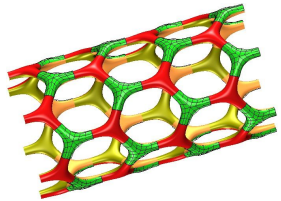
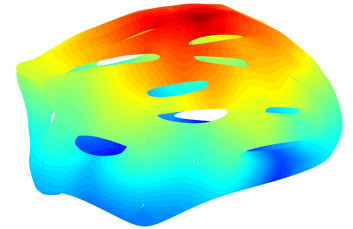
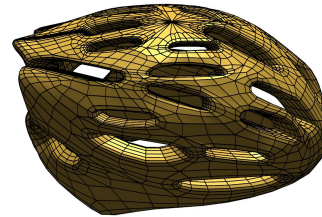
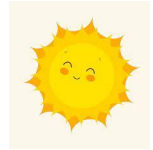
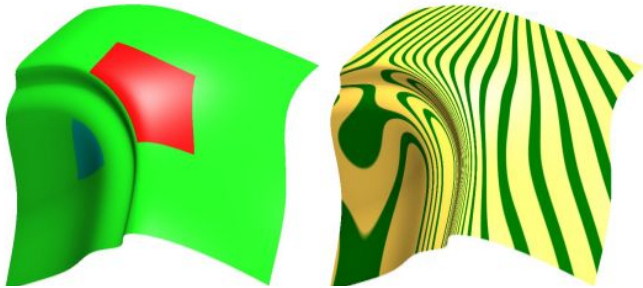
[What do we do?](#)

We Create, View, and Manipulate Splines

Polyhedral-net Splines for Geometry and Analysis

Jorg Peters

Blender [Add-on](#) AMC ToMS 2023: C++ PnS2 PnS3 PnS_IGA



Jorg Peters U of Florida

Joint work with K Karciauskas,
Bhaskar Mishra, Seth Barber

CIRM 2024

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Polyhedral-net Surfaces for Geometry & Analysis

Jorg Peters

Engineering analysis should match an underlying designed shape and not restrict the quality of the shape. I.e. one would like finite elements matched to a geometric space optimized for generically good shape.

Since the 1980s, classic tensor-product splines have been used both to define good shape geometry and analysis functions (finite elements) on the geometry.

Polyhedral-net splines (PnS) generalize tensor-product splines by allowing additional control net patterns required for free-form surfaces: *isotropic patterns*, such as n quads surrounding a vertex, an n -gon surrounded by quads, polar configurations where many triangles join; and *preferred direction patterns*, that adjust parameter line density, such as T-junctions.

PnS2 generalize C1 bi-2 splines, generate C1 surfaces and can be output bi-3 Bezier pieces. There are two instances of PnS2 in the public domain: a Blender add-on and a ToMS distribution with output in several formats.

PnS3 generalize C2 bi-3 splines for high-end design.

PnS generalize the use of higher-order isoparametric approach from tensor-product splines. A web interface offers solving elliptic PDEs on PnS2 surfaces and using PnS2 finite elements.